

# Loops on spheres having a compact-free inner mapping group

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## Abstract

We prove that any topological loop homeomorphic to a sphere or to a real projective space and having a compact-free Lie group as the inner mapping group is homeomorphic to the circle. Moreover, we classify the differentiable 1-dimensional compact loops explicitly using the theory of Fourier series.

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## Introduction

The only known proper topological compact connected loops such that the groups  $G$  topologically generated by their left translations are locally compact and the stabilizers  $H$  of their identities in  $G$  have no non-trivial compact subgroups are homeomorphic to the 1-sphere. In [8], [9], [7], [10] it is shown that the differentiable 1-dimensional loops can be classified by pairs of real functions which satisfy a differential inequality containing these functions and their first derivatives. A main goal of this paper is to determine the functions satisfying this inequality explicitly in terms of Fourier series.

If  $L$  is a topological loop homeomorphic to a sphere or to a real projective space and having a Lie group  $G$  as the group topologically generated by the left translations such that the stabilizer of the identity of  $L$  is a compact-free Lie subgroup of  $G$ , then  $L$  is the 1-sphere and  $G$  is isomorphic to a finite covering of the group  $PSL_2(\mathbb{R})$  (cf. Theorem 4).

To decide which sections  $\sigma : G/H \rightarrow G$ , where  $G$  is a Lie group and  $H$  is a (closed) subgroup of  $G$  containing no normal subgroup  $\neq 1$  of  $G$  correspond to loops we use systematically a theorem of R. Baer (cf. [3] and [8], Proposition 1.6, p. 18). This statement says that  $\sigma$  corresponds

to a loop if and only if the image  $\sigma(G/H)$  is also the image for any section  $G/H^a \rightarrow G$ , where  $H = a^{-1}Ha$  and  $a \in G$ . As one of the applications of this we derive in a different way the differential inequality in [8], p. 218, in which the necessary and sufficient conditions for the existence of 1-dimensional differentiable loops are hidden.

### Basic facts in loop theory

A set  $L$  with a binary operation  $(x, y) \mapsto x * y : L \times L \rightarrow L$  and an element  $e \in L$  such that  $e * x = x * e = x$  for all  $x \in L$  is called a loop if for any given  $a, b \in L$  the equations  $a * y = b$  and  $x * a = b$  have unique solutions which we denote by  $y = a \setminus b$  and  $x = b / a$ . Every left translation  $\lambda_a : y \mapsto a * y : L \rightarrow L$ ,  $a \in L$  is a bijection of  $L$  and the set  $\Lambda = \{\lambda_a, a \in L\}$  generates a group  $G$  such that  $\Lambda$  forms a system of representatives for the left cosets  $\{xH, x \in G\}$ , where  $H$  is the stabilizer of  $e \in L$  in  $G$ . Moreover, the elements of  $\Lambda$  act on  $G/H = \{xH, x \in G\}$  such that for any given cosets  $aH$  and  $bH$  there exists precisely one left translation  $\lambda_z$  with  $\lambda_z aH = bH$ .

Conversely, let  $G$  be a group,  $H$  be a subgroup containing no normal subgroup  $\neq 1$  of  $G$  and let  $\sigma : G/H \rightarrow G$  be a section with  $\sigma(H) = 1 \in G$  such that the set  $\sigma(G/H)$  of representatives for the left cosets of  $H$  in  $G$  generates  $G$  and acts sharply transitively on the space  $G/H$  (cf. [8], p. 18). Such a section we call a sharply transitive section. Then the multiplication defined by  $xH * yH = \sigma(xH)yH$  on the factor space  $G/H$  or by  $x * y = \sigma(xyH)$  on  $\sigma(G/H)$  yields a loop  $L(\sigma)$ . The group  $G$  is isomorphic to the group generated by the left translations of  $L(\sigma)$ .

We call the group generated by the mappings  $\lambda_{x,y} = \lambda_{xy}^{-1} \lambda_x \lambda_y : L \rightarrow L$ , for all  $x, y \in L$ , the inner mapping group of the loop  $L$  (cf. [8], Definition 1.30, p. 33). According to Lemma 1.31 in [8], p. 33, this group coincides with the stabilizer  $H$  of the identity of  $L$  in the group generated by the left translations of  $L$ .

A locally compact loop  $L$  is almost topological if it is a locally compact space and the multiplication  $* : L \times L \rightarrow L$  is continuous. Moreover, if the maps  $(a, b) \mapsto b/a$  and  $(a, b) \mapsto a \setminus b$  are continuous then  $L$  is a topological loop. An (almost) topological loop  $L$  is connected if and only if the group topologically generated by the left translations is connected. We call the loop  $L$  strongly almost topological if the group topologically generated by its left translations is locally compact and the corresponding sharply transitive section  $\sigma : G/H \rightarrow G$ , where  $H$  is the stabilizer of  $e \in L$  in  $G$ , is continuous.

If a loop  $L$  is a connected differentiable manifold such that the multiplication  $* : L \times L \rightarrow L$  is continuously differentiable, then  $L$  is an

almost  $\mathcal{C}^1$ -differentiable loop (cf. Definition 1.24 in [8], p. 31). Moreover, if the mappings  $(a, b) \mapsto b/a$  and  $(a, b) \mapsto a \setminus b$  are also continuously differentiable, then the loop  $L$  is a  $\mathcal{C}^1$ -differentiable loop. If an almost  $\mathcal{C}^1$ -differentiable loop has a Lie group  $G$  as the group topologically generated by its left translations, then the sharply transitive section  $\sigma : G/H \rightarrow G$  is  $\mathcal{C}^1$ -differentiable. Conversely, any continuous, respectively  $\mathcal{C}^1$ -differentiable sharply transitive section  $\sigma : G/H \rightarrow G$  yields an almost topological, respectively an almost  $\mathcal{C}^1$ -differentiable loop.

It is known that for any (almost) topological loop  $L$  homeomorphic to a connected topological manifold there exists a universal covering loop  $\tilde{L}$  such that the covering mapping  $p : \tilde{L} \rightarrow L$  is an epimorphism. The inverse image  $p^{-1}(e) = \text{Ker}(p)$  of the identity element  $e$  of  $L$  is a central discrete subgroup  $Z$  of  $\tilde{L}$  and it is naturally isomorphic to the fundamental group of  $L$ . If  $Z'$  is a subgroup of  $Z$ , then the factor loop  $\tilde{L}/Z'$  is a covering loop of  $L$  and any covering loop of  $L$  is isomorphic to a factor loop  $\tilde{L}/Z'$  with a suitable subgroup  $Z'$  (see [5]).

If  $L'$  is a covering loop of  $L$ , then Lemma 1.34 in [8], p. 33, clarifies the relation between the group topologically generated by the left translations of  $L'$  and the group topologically generated by the left translations of  $L$ :

*Let  $L$  be a topological loop homeomorphic to a connected topological manifold. Let the group  $G$  topologically generated by the left translations  $\lambda_a, a \in L$ , of  $L$  be a Lie group. Let  $\tilde{L}$  be the universal covering of  $L$  and  $Z \subseteq \tilde{L}$  be the fundamental group of  $L$ . Then the group  $\tilde{G}$  topologically generated by the left translations  $\tilde{\lambda}_u, u \in \tilde{L}$ , of  $\tilde{L}$  is the covering group of  $G$  such that the kernel of the covering mapping  $\varphi : \tilde{G} \rightarrow G$  is  $Z^* = \{\tilde{\lambda}_z, z \in Z\}$  and  $Z^*$  is isomorphic to  $Z$ . If we identify  $\tilde{L}$  and  $L$  with the homogeneous spaces  $\tilde{G}/\tilde{H}$  and  $G/H$ , where  $H$  or  $\tilde{H}$  is the stabilizer of the identity of  $L$  in  $G$  or of  $\tilde{L}$  in  $\tilde{G}$ , respectively, then  $\varphi(\tilde{H}) = H$ ,  $\tilde{H} \cap Z^* = \{1\}$ , and  $\tilde{H}$  is isomorphic to  $H$ .*

### Compact topological loops on the 3-dimensional sphere

**Proposition 1.** *There is no almost topological proper loop  $L$  homeomorphic to the 3-sphere  $\mathcal{S}_3$  or to the 3-dimensional real projective space  $\mathcal{P}_3$  such that the group  $G$  topologically generated by the left translations of  $L$  is isomorphic to the group  $SL_2(\mathbb{C})$  or to the group  $PSL_2(\mathbb{C})$ , respectively.*

*Proof.* We assume that there is an almost topological loop  $L$  homeomorphic to  $\mathcal{S}_3$  such that the group topologically generated by its left

translations is isomorphic to  $G = SL_2(\mathbb{C})$ . Then there exists a continuous sharply transitive section  $\sigma : SL_2(\mathbb{C})/H \rightarrow SL_2(\mathbb{C})$ , where  $H$  is a connected compact-free 3-dimensional subgroup of  $SL_2(\mathbb{C})$ . According to [2], pp. 273-278, there is a one-parameter family of connected compact-free 3-dimensional subgroups  $H_r$ ,  $r \in \mathbb{R}$  of  $SL_2(\mathbb{C})$  such that  $H_{r_1}$  is conjugate to  $H_{r_2}$  precisely if  $r_1 = r_2$ . Hence we may assume that the stabilizer  $H$  has one of the following shapes

$$H_r = \left\{ \begin{pmatrix} \exp[(ri-1)a] & b \\ 0 & \exp[(1-ri)a] \end{pmatrix}; a \in \mathbb{R}, b \in \mathbb{C} \right\}, \quad r \in \mathbb{R},$$

(cf. Theorem 1.11 in [8], p. 21). For each  $r \in \mathbb{R}$  the section  $\sigma_r : G/H_r \rightarrow G$  corresponding to a loop  $L_r$  is given by

$$\begin{pmatrix} x & y \\ -\bar{y} & \bar{x} \end{pmatrix} H_r \mapsto \begin{pmatrix} x & y \\ -\bar{y} & \bar{x} \end{pmatrix} \begin{pmatrix} \exp[(ri-1)f(x,y)] & g(x,y) \\ 0 & \exp[(1-ri)f(x,y)] \end{pmatrix},$$

where  $x, y \in \mathbb{C}$ ,  $x\bar{x} + y\bar{y} = 1$  such that  $f(x, y) : S^3 \rightarrow \mathbb{R}$ ,  $g(x, y) : S^3 \rightarrow \mathbb{C}$  are continuous functions with  $f(1, 0) = 0 = g(1, 0)$ . Since  $\sigma_r$  is a sharply transitive action for each  $r \in \mathbb{R}$  the image  $\sigma_r(G/H_r)$  forms a system of representatives for all cosets  $xH_r^\gamma$ ,  $\gamma \in G$ . This means for all given  $c, d \in \mathbb{C}^2$ ,  $c\bar{c} + d\bar{d} = 1$  each coset

$$\begin{pmatrix} u & v \\ -\bar{v} & \bar{u} \end{pmatrix} \begin{pmatrix} c & d \\ -\bar{d} & \bar{c} \end{pmatrix} H_r \begin{pmatrix} \bar{c} & -d \\ \bar{d} & c \end{pmatrix},$$

where  $u, v \in \mathbb{C}$ ,  $u\bar{u} + v\bar{v} = 1$ , contains precisely one element of  $\sigma_r(G/H_r)$ . This is the case if and only if for all given  $c, d, u, v \in \mathbb{C}$  with  $u\bar{u} + v\bar{v} = 1 = c\bar{c} + d\bar{d}$  there exists a unique triple  $(x, y, q) \in \mathbb{C}^3$  with  $x\bar{x} + y\bar{y} = 1$  and a real number  $m$  such that the following matrix equation holds:

$$\begin{pmatrix} \bar{u}\bar{c} - \bar{v}d & -ud - v\bar{c} \\ \bar{v}c + \bar{u}\bar{d} & uc - v\bar{d} \end{pmatrix} \begin{pmatrix} x & y \\ -\bar{y} & \bar{x} \end{pmatrix} \begin{pmatrix} \exp[(ri-1)f(x,y)] & g(x,y) \\ 0 & \exp[(1-ri)f(x,y)] \end{pmatrix} \\ = \begin{pmatrix} \exp[(ri-1)m] & q \\ 0 & \exp[(1-ri)m] \end{pmatrix} \begin{pmatrix} \bar{c} & -d \\ \bar{d} & c \end{pmatrix}. \quad (1)$$

The (1,1)- and (2,1)-entry of the matrix equation (1) give the following system  $A$  of equations:

$$[(\bar{u}x + \bar{v}y)\bar{c} + (u\bar{y} - \bar{v}x)d] \exp[(ri-1)f(x,y)] = \exp[(ri-1)m]\bar{c} + q\bar{d} \quad (2)$$

$$[(\bar{v}x - u\bar{y})c + (\bar{u}x + \bar{v}y)\bar{d}] \exp[(ri-1)f(x,y)] = \exp[(1-ri)m]\bar{d}. \quad (3)$$

If we take  $c$  and  $d$  as independent variables the system  $A$  yields the following system  $B$  of equations:

$$(\bar{u}x + \bar{v}y) \exp[irf(x,y)] \exp[-f(x,y)] = \exp(irm) \exp(-m) \quad (4)$$

$$(u\bar{y} - \bar{v}x) \exp[(ri - 1)f(x, y)]d = \bar{d}q \quad (5)$$

$$(\bar{u}x + v\bar{y}) \exp[irf(x, y)] \exp[-f(x, y)] = \exp(m) \exp(-irm). \quad (6)$$

Since equation (5) must be satisfied for all  $d \in \mathbb{C}$  we obtain  $q = 0$ . From equation (4) it follows

$$\bar{u}x + v\bar{y} = \exp(irm) \exp(-m) \exp[-irf(x, y)] \exp[f(x, y)]. \quad (7)$$

Putting (7) into (6) one obtains

$$\exp(irm) \exp(-m) = \exp(m) \exp(-irm) \quad (8)$$

which is equivalent to

$$\exp[2(ir - 1)m] = 1. \quad (9)$$

The equation (9) is satisfied if and only if  $m = 0$ . Hence the matrix equation (1) reduces to the matrix equation

$$\begin{pmatrix} x & y \\ -\bar{y} & \bar{x} \end{pmatrix} \begin{pmatrix} \exp[(ri - 1)f(x, y)] & g(x, y) \\ 0 & \exp[(1 - ri)f(x, y)] \end{pmatrix} = \begin{pmatrix} u & v \\ -\bar{v} & \bar{u} \end{pmatrix}.$$

and therefore the matrix

$$M = \begin{pmatrix} \exp[(ri - 1)f(x, y)] & g(x, y) \\ 0 & \exp[(1 - ri)f(x, y)] \end{pmatrix}$$

is an element of  $SU_2(\mathbb{C})$ . This is the case if and only if  $f(x, y) = 0 = g(x, y)$  for all  $(x, y) \in \mathbb{C}^2$  with  $x\bar{x} + y\bar{y} = 1$ . Since for each  $r \in \mathbb{R}$  the loop  $L_r$  is isomorphic to the loop  $L_r(\sigma_r)$ , hence to the group  $SU_2(\mathbb{C})$ , there is no connected almost topological proper loop  $L$  homeomorphic to  $\mathcal{S}_3$  such that the group topologically generated by its left translations is isomorphic to the group  $SL_2(\mathbb{C})$ .

The universal covering of an almost topological proper loop  $L$  homeomorphic to the real projective space  $\mathcal{P}_3$  is an almost topological proper loop  $\tilde{L}$  homeomorphic to  $\mathcal{S}_3$ . If the group topologically generated by the left translations of  $L$  is isomorphic to  $PSL_2(\mathbb{C})$  then the group topologically generated by the left translations of  $\tilde{L}$  is isomorphic to  $SL_2(\mathbb{C})$ . Since no proper loop  $\tilde{L}$  exists the Proposition is proved.  $\square$

**Proposition 2.** *There is no almost topological proper loop  $L$  homeomorphic to the 3-dimensional real projective space  $\mathcal{P}_3$  or to the 3-sphere  $\mathcal{S}_3$  such that the group  $G$  topologically generated by the left translations of  $L$  is isomorphic to the group  $SL_3(\mathbb{R})$  or to the universal covering group  $\widetilde{SL_3(\mathbb{R})}$ , respectively.*

*Proof.* First we assume that there exists an almost topological loop  $L$  homeomorphic to  $\mathcal{P}_3$  such that the group topologically generated by its left translations is isomorphic to  $G = SL_3(\mathbb{R})$ . Then there is a continuous sharply transitive section  $\sigma : SL_3(\mathbb{R})/H \rightarrow SL_3(\mathbb{R})$ , where  $H$  is a connected compact-free 5-dimensional subgroup of  $SL_3(\mathbb{R})$ . According to Theorem 2.7, p. 187, in [4] and to Theorem 1.11, p. 21, in [8] we may assume that

$$H = \left\{ \begin{pmatrix} a & k & v \\ 0 & b & l \\ 0 & 0 & (ab)^{-1} \end{pmatrix} ; a > 0, b > 0, k, l, v \in \mathbb{R} \right\}. \quad (10)$$

Using Euler angles every element of  $SO_3(\mathbb{R})$  can be represented by the following matrix

$$g(t, u, z) := \begin{pmatrix} \cos t & \sin t & 0 \\ -\sin t & \cos t & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos z & \sin z \\ 0 & -\sin z & \cos z \end{pmatrix} \begin{pmatrix} \cos u & \sin u & 0 \\ -\sin u & \cos u & 0 \\ 0 & 0 & 1 \end{pmatrix} =$$

$$\begin{pmatrix} \cos t \cos u - \sin t \cos z \sin u & \cos t \sin u + \sin t \cos z \cos u & \sin t \sin z \\ -\sin t \cos u - \cos t \cos z \sin u & -\sin t \sin u + \cos t \cos z \cos u & \cos t \sin z \\ \sin z \sin u & -\sin z \cos u & \cos z \end{pmatrix},$$

where  $t, u \in [0, 2\pi]$  and  $z \in [0, \pi]$ .

The section  $\sigma : SL_3(\mathbb{R})/H \rightarrow SL_3(\mathbb{R})$  is given by

$$g(t, u, z)H \mapsto g(t, u, z) \begin{pmatrix} f_1(t, u, z) & f_2(t, u, z) & f_3(t, u, z) \\ 0 & f_4(t, u, z) & f_5(t, u, z) \\ 0 & 0 & f_1^{-1}(t, u, z)f_4^{-1}(t, u, z) \end{pmatrix}, \quad (11)$$

where  $t, u \in [0, 2\pi]$ ,  $z \in [0, \pi]$  and  $f_i(t, u, z) : [0, 2\pi] \times [0, 2\pi] \times [0, \pi] \rightarrow \mathbb{R}$  are continuous functions such that for  $i \in \{1, 4\}$  the functions  $f_i$  are positive with  $f_i(0, 0, 0) = 1$  and for  $j = \{2, 3, 5\}$  the functions  $f_j(t, u, z)$  satisfy that  $f_j(0, 0, 0) = 0$ . As  $\sigma$  is sharply transitive the image  $\sigma(SL_3(\mathbb{R})/H)$  forms a system of representatives for all cosets  $xH^\delta$ ,  $\delta \in SL_3(\mathbb{R})$ . Since the elements  $x$  and  $\delta$  can be chosen in the group  $SO_3(\mathbb{R})$  we may take  $x$  as the matrix

$$\begin{pmatrix} \cos q \cos r - \sin q \sin r \cos p & \cos q \sin r + \sin q \cos r \cos p & \sin q \sin p \\ -\sin q \cos r - \cos q \sin r \cos p & -\sin q \sin r + \cos q \cos r \cos p & \cos q \sin p \\ \sin p \sin r & -\sin p \cos r & \cos p \end{pmatrix}$$

and  $\delta$  as the matrix

$$\begin{pmatrix} \cos \alpha \cos \beta - \sin \alpha \sin \beta \cos \gamma & \cos \alpha \sin \beta + \sin \alpha \cos \beta \cos \gamma & \sin \alpha \sin \gamma \\ -\sin \alpha \cos \beta - \cos \alpha \sin \beta \cos \gamma & -\sin \alpha \sin \beta + \cos \alpha \cos \beta \cos \gamma & \cos \alpha \sin \gamma \\ \sin \gamma \sin \beta & -\sin \gamma \cos \beta & \cos \gamma \end{pmatrix},$$

where  $q, r, \alpha, \beta \in [0, 2\pi]$  and  $p, \gamma \in [0, \pi]$ . The image  $\sigma(SL_3(\mathbb{R})/H)$  forms for all given  $\delta \in SO_3(\mathbb{R})$  and  $x \in SO_3(\mathbb{R})$  a system of representatives for

the cosets  $xH^\delta$  if and only if there exists unique angles  $t, u \in [0, 2\pi]$  and  $z \in [0, \pi]$  and unique positive real numbers  $a, b$  as well as unique real numbers  $k, l, v$  such that the following equation holds

$$\delta x^{-1} g(t, u, z) f = h \delta, \quad (12)$$

where the matrices  $\delta, x$  have the form as above,

$$f = \begin{pmatrix} f_1(t, u, z) & f_2(t, u, z) & f_3(t, u, z) \\ 0 & f_4(t, u, z) & f_5(t, u, z) \\ 0 & 0 & f_1^{-1}(t, u, z) f_4^{-1}(t, u, z) \end{pmatrix}$$

and

$$h = \begin{pmatrix} a & k & v \\ 0 & b & l \\ 0 & 0 & (ab)^{-1} \end{pmatrix}.$$

Comparing the first column of the left and the right side of the equation (12) we obtain the following three equations:

$$\begin{aligned} f_1(t, u, z) \{ & [(\cos \alpha \cos \beta - \sin \alpha \sin \beta \cos \gamma)(\cos r \cos q - \sin r \sin q \cos p) + \\ & (\cos \alpha \sin \beta + \sin \alpha \cos \beta \cos \gamma)(\sin r \cos q + \cos r \sin q \cos p) + \\ & \sin \alpha \sin \gamma \sin p \sin q](\cos t \cos u - \sin t \sin u \cos z) - \\ & [-(\cos \alpha \cos \beta - \sin \alpha \sin \beta \cos \gamma)(\cos r \sin q + \sin r \cos q \cos p) + \\ & (\cos \alpha \sin \beta + \sin \alpha \cos \beta \cos \gamma)(-\sin r \sin q + \cos r \cos q \cos p) + \\ & \sin \alpha \sin \gamma \sin p \cos q](\sin t \cos u + \cos t \sin u \cos z) + \\ & [(\cos \alpha \cos \beta - \sin \alpha \sin \beta \cos \gamma) \sin r \sin p - \\ & (\cos \alpha \sin \beta + \sin \alpha \cos \beta \cos \gamma) \cos r \sin p + \sin \alpha \sin \gamma \cos p] \sin z \sin u \} = \\ & a(\cos \alpha \cos \beta - \sin \alpha \sin \beta \cos \gamma) - k(\sin \alpha \cos \beta + \cos \alpha \sin \beta \cos \gamma) + \\ & v \sin \gamma \sin \beta, \end{aligned}$$

$$\begin{aligned} f_1(t, u, z) \{ & [-(\sin \alpha \cos \beta + \cos \alpha \sin \beta \cos \gamma)(\cos r \cos q - \sin r \sin q \cos p) - \\ & (-\sin \alpha \sin \beta + \cos \alpha \cos \beta \cos \gamma)(\sin r \cos q + \cos r \sin q \cos p) + \\ & \cos \alpha \sin \gamma \sin p \sin q](\cos t \cos u - \sin t \sin u \cos z) - \\ & [(\sin \alpha \cos \beta + \cos \alpha \sin \beta \cos \gamma)(\cos r \sin q + \sin r \cos q \cos p) + \\ & (-\sin \alpha \sin \beta + \cos \alpha \cos \beta \cos \gamma)(-\sin r \sin q + \cos r \cos q \cos p) + \\ & \cos \alpha \sin \gamma \sin p \cos q](\sin t \cos u + \cos t \sin u \cos z) + \\ & [-(\sin \alpha \cos \beta + \cos \alpha \sin \beta \cos \gamma) \sin r \sin p - (\cos \alpha \cos \beta \cos \gamma - \sin \alpha \sin \beta) \\ & \cos r \sin p + \cos \alpha \sin \gamma \cos p] \sin z \sin u \} = \\ & -b(\sin \alpha \cos \beta + \cos \alpha \sin \beta \cos \gamma) + l \sin \gamma \sin \beta, \end{aligned}$$

$$\begin{aligned} f_1(t, u, z) \{ & [(\cos r \cos q - \sin r \sin q \cos p) \sin \gamma \sin \beta - \\ & (\sin r \cos q + \cos r \sin q \cos p) \sin \gamma \cos \beta + \cos \gamma \sin p \sin q] \\ & (\cos t \cos u - \sin t \sin u \cos z) + [(\cos r \sin q + \sin r \cos q \cos p) \sin \gamma \sin \beta + \\ & (-\sin r \sin q + \cos r \cos q \cos p) \sin \gamma \cos \beta + \cos \gamma \sin p \cos q] \end{aligned}$$

$$\begin{aligned}
& (\sin t \cos u + \cos t \sin u \cos z) + \\
& [(\sin \gamma \sin \beta \sin r \sin p + \sin \gamma \cos \beta \cos r \sin p) + \cos \gamma \cos p] \sin z \sin u \} = \\
& (ab)^{-1} \sin \gamma \sin \beta.
\end{aligned}$$

If we take  $\sin \gamma \sin \beta$  and  $\cos \gamma$  as independent variables the third equation turns to the following equations

$$\begin{aligned}
0 &= f_1(t, u, z) [\sin p \sin q (\cos t \cos u - \sin t \sin u \cos z) - \\
& \sin p \cos q (\sin t \cos u + \cos t \sin u \cos z) + \cos p \sin z \sin u] \quad (13) \\
(ab)^{-1} &= \{[(\cos r \cos q - \sin r \sin q \cos p)(\cos t \cos u - \sin t \sin u \cos z) + \\
& (\cos r \sin q + \sin r \cos q \cos p)(\sin t \cos u + \cos t \sin u \cos z) + \\
& \sin r \sin p \sin z \sin u] - \\
& \frac{\cos \beta}{\sin \beta} [(\sin r \cos q + \cos r \sin q \cos p)(\cos t \cos u - \sin t \sin u \cos z) - \\
& (-\sin r \sin q + \cos r \cos q \cos p)(\sin t \cos u + \cos t \sin u \cos z) - \\
& \cos r \sin p \sin z \sin u]\} f_1(t, u, z). \quad (14)
\end{aligned}$$

If we take  $\cos \alpha \sin \beta \cos \gamma$ ,  $\sin \beta \sin \gamma$  as independent variables from the second equation it follows

$$\begin{aligned}
l &= \frac{\cos \alpha}{\sin \beta} f_1(t, u, z) [\sin p \sin q (\cos t \cos u - \sin t \sin u \cos z) - \\
& \sin p \cos q (\sin t \cos u + \cos t \sin u \cos z) + \cos p \sin z \sin u] \quad (15) \\
-b &= \{[-(\cos r \cos q - \sin r \sin q \cos p)(\cos t \cos u - \sin t \sin u \cos z) - \\
& (\cos r \sin q + \sin r \cos q \cos p)(\sin t \cos u + \cos t \sin u \cos z) - \\
& \sin r \sin p \sin z \sin u] - \\
& \frac{\cos \beta}{\sin \beta} [(\sin r \cos q + \cos r \sin q \cos p)(\cos t \cos u - \sin t \sin u \cos z) - \\
& (-\sin r \sin q + \cos r \cos q \cos p)(\sin t \cos u + \cos t \sin u \cos z) - \\
& \cos r \sin p \sin z \sin u]\} f_1(t, u, z). \quad (16)
\end{aligned}$$

If we choose  $\sin \alpha \sin \beta \cos \gamma$ ,  $\sin \beta \sin \gamma$  as independent variables the first equation yields

$$\begin{aligned}
v &= \frac{\sin \alpha}{\sin \beta} f_1(t, u, z) [\sin p \sin q (\cos t \cos u - \sin t \sin u \cos z) - \\
& \sin p \cos q (\sin t \cos u + \cos t \sin u \cos z) + \cos p \sin z \sin u] \quad (17)
\end{aligned}$$

$$\begin{aligned}
a + k \frac{\cos \alpha}{\sin \alpha} &= \{[(\cos r \cos q - \sin r \sin q \cos p)(\cos t \cos u - \sin t \sin u \cos z) - \\
& (\cos r \sin q + \sin r \cos q \cos p)(\sin t \cos u + \cos t \sin u \cos z) + \\
& \sin r \sin p \sin z \sin u] - \\
& \frac{\cos \beta}{\sin \beta} [(\sin r \cos q + \cos r \sin q \cos p)(\cos t \cos u - \sin t \sin u \cos z) - \\
& (-\sin r \sin q + \cos r \cos q \cos p)(\sin t \cos u + \cos t \sin u \cos z) - \\
& \cos r \sin p \sin z \sin u]\} f_1(t, u, z). \quad (18)
\end{aligned}$$



Since  $f_1(t, u, z) > 0$  from equation (13) it follows that

$$0 = \sin p \sin q (\cos t \cos u - \sin t \sin u \cos z) + \sin p \cos q (\sin t \cos u + \cos t \sin u \cos z) + \cos p \sin z \sin u. \quad (19)$$

Using this it follows from (15) that  $l = 0$  holds and from equation (17) that  $v = 0$ . Since the equation (14) must be satisfied for all  $\beta \in [0, 2\pi]$  we have

$$(ab)^{-1} = [(\cos r \cos q - \sin r \sin q \cos p)(\cos t \cos u - \sin t \sin u \cos z) + (\cos r \sin q + \sin r \cos q \cos p)(\sin t \cos u + \cos t \sin u \cos z) + \sin r \sin p \sin z \sin u] f_1(t, u, z) \quad (20)$$

$$0 = [(\sin r \cos q + \cos r \sin q \cos p)(\cos t \cos u - \sin t \sin u \cos z) - (-\sin r \sin q + \cos r \cos q \cos p)(\sin t \cos u + \cos t \sin u \cos z) - \cos r \sin p \sin z \sin u]. \quad (21)$$

Using equation (21) and comparing the equations (20) and (16) we obtain that  $(ab)^{-1} = b$ . With equation (21) the equation (18) turns to

$$a + k \frac{\cos \alpha}{\sin \alpha} = [(\cos r \cos q - \sin r \sin q \cos p)(\cos t \cos u - \sin t \sin u \cos z) - (\cos r \sin q + \sin r \cos q \cos p)(\sin t \cos u + \cos t \sin u \cos z) + \sin r \sin p \sin z \sin u] f_1(t, u, z). \quad (22)$$

Since the equation (22) must be satisfied for all  $\alpha \in [0, 2\pi]$  we obtain  $k = 0$ . Using this, the equations (22) and (20) yield  $(ab)^{-1} = a$ . Since  $1 = ab(ab)^{-1} = a^3$  it follows that  $a = 1$  and hence the matrix  $h$  is the identity. But then the matrix equation (12) turns to the matrix equation

$$g(t, u, z) f = x.$$

As  $x$  and  $g(t, u, z)$  are elements of  $SO_3(\mathbb{R})$  one has  $f = xg^{-1}(t, u, z) \in SO_3(\mathbb{R})$ . But then  $f$  is the identity, which means that

$$f_1(t, u, z) = 1 = f_4(t, u, z), \quad f_2(t, u, z) = f_3(t, u, z) = f_5(t, u, z) = 0,$$

for all  $t, u \in [0, 2\pi]$  and  $z \in [0, \pi]$ . Since the loop  $L$  is isomorphic to the loop  $L(\sigma)$  and  $L(\sigma) \cong SO_3(\mathbb{R})$  there is no connected almost topological proper loop  $L$  homeomorphic to  $\mathcal{P}_3$  such that the group topologically generated by its left translations is isomorphic to  $SL_3(\mathbb{R})$ .

Now we assume that there is an almost topological loop  $L$  homeomorphic to  $\mathcal{S}_3$  such that the group  $G$  topologically generated by its left translations is isomorphic to the universal covering group  $\widetilde{SL}_3(\mathbb{R})$ . Then the stabilizer  $H$  of the identity of  $L$  may be chosen as the group (10). Then there exists a local section  $\sigma : U/H \rightarrow G$ , where  $U$  is a suitable neighbourhood of  $H$  in  $G/H$  which has the shape (11) with sufficiently small  $t, u \in [0, 2\pi]$ ,  $z \in [0, \pi]$  and continuous functions  $f_i(t, u, z) :$

$[0, 2\pi] \times [0, 2\pi] \times [0, \pi] \rightarrow \mathbb{R}$  satisfying the same conditions as there. The image  $\sigma(U/H)$  is a local section for the space of the left cosets  $\{xH^\delta; x \in G, \delta \in G\}$  precisely if for all suitable matrices  $x := g(q, r, p)$  with sufficiently small  $(q, r, p) \in [0, 2\pi] \times [0, 2\pi] \times [0, \pi]$  there exist a unique element  $g(t, u, z) \in Spin_3(\mathbb{R})$  with sufficiently small  $(t, u, z) \in [0, 2\pi] \times [0, 2\pi] \times [0, \pi]$  and unique positive real numbers  $a, b$  as well as unique real numbers  $k, l, v$  such that the matrix equation (12) holds. Then we see as in the case of the group  $SL_3(\mathbb{R})$  that for small  $x$  and  $g(t, u, z)$  the matrix  $f$  is the identity. Therefore any subloop  $T$  of  $L$  which is homeomorphic to  $\mathcal{S}_1$  is locally commutative. Then according to [8], Corollary 18.19, p. 248, each subloop  $T$  is isomorphic to a 1-dimensional torus group. It follows that the restriction of the matrix  $f$  to  $T$  is the identity. Since  $L$  is covered by such 1-dimensional tori the matrix  $f$  is the identity for all elements of  $\mathcal{S}_3$ . Hence there is no proper loop  $L$  homeomorphic to  $\mathcal{S}_3$  such that the group  $G$  topologically generated by its left translations is isomorphic to the universal covering group  $\widetilde{SL_3(\mathbb{R})}$ .  $\square$

### Compact loops with compact-free inner mapping groups

**Proposition 3.** *Let  $L$  be an almost topological loop homeomorphic to a compact connected Lie group  $K$ . Then the group  $G$  topologically generated by the left translations of  $L$  cannot be isomorphic to a split extension of a solvable group  $R$  homeomorphic to  $\mathbb{R}^n$  ( $n \geq 1$ ) by the group  $K$ .*

*Proof.* Denote by  $H$  the stabilizer of the identity of  $L$  in  $G$ . If  $G$  has the structure as in the assertion then the elements of  $G$  can be represented by the pairs  $(k, r)$  with  $k \in K$  and  $r \in R$ . Since  $L$  is homeomorphic to  $K$  the loop  $L$  is isomorphic to the loop  $L(\sigma)$  given by a sharply transitive section  $\sigma : G/H \rightarrow G$  the image of which is the set  $\mathfrak{S} = \{(k, f(k)); k \in K\}$ , where  $f$  is a continuous function from  $K$  into  $R$  with  $f(1) = 1 \in R$ . The multiplication of  $(L(\sigma), *)$  on  $\mathfrak{S}$  is given by  $(x, f(x)) * (y, f(y)) = \sigma((xy, f(x)f(y))H)$ .

Let  $T$  be a 1-dimensional torus of  $K$ . Then the set  $\{(t, f(t)); t \in T\}$  topologically generates a compact subloop  $\tilde{T}$  of  $L(\sigma)$  such that the group topologically generated by its left translations has the shape  $TU$  with  $T \cap U = 1$ , where  $U$  is a normal solvable subgroup of  $TU$  homeomorphic to  $\mathbb{R}^n$  for some  $n \geq 1$ . The multiplication  $*$  in the subloop  $\tilde{T}$  is given by

$$(x, f(x)) * (y, f(y)) = \sigma((xy, f(x)f(y))H) = (xy, f(xy)),$$

where  $x, y \in T$ . Hence  $\tilde{T}$  is a subloop homeomorphic to a 1-sphere which has a solvable Lie group  $S$  as the group topologically generated by the

left translations. It follows that  $\tilde{T}$  is a 1-dimensional torus group since otherwise the group  $S$  would be not solvable (cf. [8], Proposition 18.2, p. 235). As  $f : \tilde{T} \rightarrow U$  is a homomorphism and  $U$  is homeomorphic to  $\mathbb{R}^n$  it follows that the restriction of  $f$  to  $\tilde{T}$  is the constant function  $f(\tilde{T}) = 1$ . Since the exponential map of a compact group is surjective any element of  $K$  is contained in a one-parameter subgroup of  $K$ . It follows  $f(K) = 1$  and  $L$  is the group  $K$  which is a contradiction.  $\square$

**Theorem 4.** *Let  $L$  be an almost topological proper loop homeomorphic to a sphere or to a real projective space. If the group  $G$  topologically generated by the left translations of  $L$  is a Lie group and the stabilizer  $H$  of the identity of  $L$  in  $G$  is a compact-free subgroup of  $G$ , then  $L$  is homeomorphic to the 1-sphere and  $G$  is a finite covering of the group  $PSL_2(\mathbb{R})$ .*

*Proof.* If  $\dim L = 1$  then according to Brouwer's theorem (cf. [11], 96.30, p. 639) the transitive group  $G$  on  $S_1$  is a finite covering of  $PSL_2(\mathbb{R})$ .

Now let  $\dim L > 1$ . Since the universal covering of the  $n$ -dimensional real projective space is the  $n$ -sphere  $\mathcal{S}_n$  we may assume that  $L$  is homeomorphic to  $\mathcal{S}_n$ ,  $n \geq 2$ . Since  $L$  is a multiplication with identity  $e$  on  $\mathcal{S}_n$  one has  $n \in \{3, 7\}$  (cf. [1]).

Any maximal compact subgroup  $K$  of  $G$  acts transitively on  $L$  (cf. [11], 96.19, p. 636). As  $H \cap K = \{1\}$  the group  $K$  operates sharply transitively on  $L$ . Since there is no compact group acting sharply transitively on the 7-sphere (cf. [11], 96.21, p. 637), the loop  $L$  is homeomorphic to the 3-sphere. The only compact group homeomorphic to the 3-sphere is the unitary group  $SU_2(\mathbb{C})$ . If the group  $G$  were not simple, then  $G$  would be a semidirect product of the at most 3-dimensional solvable radical  $R$  with the group  $SU_2(\mathbb{C})$  (cf. [4], p. 187 and Theorem 2.1, p. 180). But according to Proposition 3 such a group cannot be the group topologically generated by the left translations of  $L$ . Hence  $G$  is a non-compact Lie group the Lie algebra of which is simple. But then  $G$  is isomorphic either to the group  $SL_2(\mathbb{C})$  or to the universal covering of the group  $SL_3(\mathbb{R})$ . It follows from Proposition 1 and 2 that no of these groups can be the group topologically generated by the left translations of an almost topological proper loop  $L$ .  $\square$

### **The classification of 1-dimensional compact connected $\mathcal{C}^1$ -loops**

If  $L$  is a connected strongly almost topological 1-dimensional compact loop, then  $L$  is homeomorphic to the 1-sphere and the group topologically generated by its left translations is a finite covering of the group  $PSL_2(\mathbb{R})$

(cf. Proposition 18.2 in [8], p. 235). We want to classify explicitly all 1-dimensional  $\mathcal{C}^1$ -differentiable compact connected loops which have either the group  $PSL_2(\mathbb{R})$  or  $SL_2(\mathbb{R})$  as the group topologically generated by the left translations.

First we classify the 1-dimensional compact connected loops having  $G = SL_2(\mathbb{R})$  as the group topologically generated by their left translations. Since the stabilizer  $H$  is compact free and may be chosen as the group of upper triangular matrices (see Theorem 1.11, in [8], p. 21) this is equivalent to the classification of all loops  $L(\sigma)$  belonging to the sharply transitive  $\mathcal{C}^1$ -differentiable sections

$$\sigma : \begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} \left\{ \begin{pmatrix} a & b \\ 0 & a^{-1} \end{pmatrix}; a > 0, b \in \mathbb{R} \right\} \rightarrow \begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} \begin{pmatrix} f(t) & g(t) \\ 0 & f^{-1}(t) \end{pmatrix} \text{ with } t \in \mathbb{R}. \quad (23)$$

**Definition 1.** Let  $\mathcal{F}$  be the set of series

$$a_0 + \sum_{k=1}^{\infty} (a_k \cos kt + b_k \sin kt), \quad t \in \mathbb{R},$$

such that

$$1 - a_0 = \sum_{k=1}^{\infty} \frac{a_k + kb_k}{1 + k^2},$$

$$a_0 > \sum_{k=1}^{\infty} \frac{ka_k - b_k}{1 + k^2} \sin kt - \frac{a_k + kb_k}{1 + k^2} \cos kt \quad \text{for all } t \in [0, 2\pi],$$

$$2a_0 \geq \sum_{k=1}^{\infty} (a_k^2 + b_k^2) \frac{k^2 - 1}{k^2 + 1}.$$

**Lemma 5.** The set  $\mathcal{F}$  consists of Fourier series of continuous functions.

*Proof.* Since  $\sum_{k=2}^{\infty} a_k^2 + b_k^2 < \frac{10}{3}a_0$  it follows from [14], p. 4, that any series in  $\mathcal{F}$  converges uniformly to a continuous function  $f$  and hence it is the Fourier series of  $f$  (cf. [14], Theorem 6.3, p. 12).  $\square$

Let  $\sigma$  be a sharply transitive section of the shape (23). Then  $f(t)$ ,  $g(t)$  are periodic continuously differentiable functions  $\mathbb{R} \rightarrow \mathbb{R}$ , such that  $f(t)$  is strictly positive with  $f(2k\pi) = 1$  and  $g(2k\pi) = 0$  for all  $k \in \mathbb{Z}$ .

As  $\sigma$  is sharply transitive the image  $\sigma(G/H)$  forms a system of representatives for the cosets  $xH^\rho$  for all  $\rho \in G$  (cf. [3]). All conjugate groups  $H^\rho$  can be already obtained if  $\rho$  is an element of  $K = \left\{ \begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix}, t \in \mathbb{R} \right\}$ . Since  $K^\kappa H^\kappa = KH^\kappa$  for any  $\kappa \in K$  the group  $K$  forms a system of representatives for the left cosets  $xH^\kappa$ .

We want to determine the left coset  $x(t)H^\kappa$  containing the element

$$\varphi(t) = \begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} \begin{pmatrix} f(t) & g(t) \\ 0 & f^{-1}(t) \end{pmatrix},$$

where  $\kappa = \begin{pmatrix} \cos \beta & \sin \beta \\ -\sin \beta & \cos \beta \end{pmatrix}$  and  $x(t) = \begin{pmatrix} \cos \eta(t) & \sin \eta(t) \\ -\sin \eta(t) & \cos \eta(t) \end{pmatrix}$ .

The element  $\varphi(t)$  lies in the left coset  $x(t)H^\kappa$  if and only if  $\varphi(t)^{\kappa^{-1}} \in x(t)^{\kappa^{-1}}H = x(t)H$ . Hence we have to solve the following matrix equation

$$\begin{pmatrix} \cos t & \sin t \\ -\sin t & \cos t \end{pmatrix} \left[ \kappa \begin{pmatrix} f(t) & g(t) \\ 0 & f^{-1}(t) \end{pmatrix} \kappa^{-1} \right] = \begin{pmatrix} \cos \eta(t) & \sin \eta(t) \\ -\sin \eta(t) & \cos \eta(t) \end{pmatrix} \begin{pmatrix} a & b \\ 0 & a^{-1} \end{pmatrix} \quad (24)$$

for suitable  $a > 0, b \in \mathbb{R}$ . Comparing both sides of the matrix equation (24) we have

$$f(t) \cos \beta (\sin t \cos \beta - \cos t \sin \beta) - g(t) \sin \beta (\sin t \cos \beta - \cos t \sin \beta) + f(t)^{-1} \sin \beta (\sin t \sin \beta + \cos t \cos \beta) = \sin \eta(t) a$$

and

$$f(t) \cos \beta (\cos t \cos \beta + \sin t \sin \beta) - g(t) \sin \beta (\cos t \cos \beta + \sin t \sin \beta) + f(t)^{-1} \sin \beta (\cos t \sin \beta - \sin t \cos \beta) = \cos \eta(t) a.$$

From this it follows

$$\tan \eta_\beta(t) = \frac{(f(t) - g(t) \tan \beta)(\tan t - \tan \beta) + f^{-1}(t) \tan \beta (1 + \tan t \tan \beta)}{(f(t) - g(t) \tan \beta)(1 + \tan t \tan \beta) + f^{-1}(t) \tan \beta (\tan \beta - \tan t)}.$$

Since  $\beta$  can be chosen in the intervall  $0 \leq \beta < \frac{\pi}{2}$  and  $\frac{\pi}{2} < \beta < \pi$  we may replace the parameter  $\tan \beta$  by any  $w \in \mathbb{R}$ .

A  $\mathcal{C}^1$ -differentiable loop  $L$  corresponding to  $\sigma$  exists if and only if the function  $t \mapsto \eta_w(t)$  is strictly increasing, i.e. if  $\eta'_w(t) > 0$  (cf. Proposition 18.3, p. 238, in [8]). The function  $a_w(t) : t \mapsto \tan \eta_w(t) : \mathbb{R} \rightarrow \mathbb{R} \cup \{\pm\infty\}$  is strictly increasing if and only if  $\eta'_w(t) > 0$  since

$$\frac{d}{dt} \tan(\eta_w(t)) = \frac{1}{\cos^2(\eta_w(t))} \eta'_w(t).$$

A straightforward calculation shows that

$$\frac{d}{dt} \tan(\eta_w(t)) = \frac{w^2 + 1}{\cos^2(t)} [w^2(g'(t)f(t) + g(t)f'(t) + g^2(t)f^2(t) + 1) + w(-2f(t)f'(t) - 2g(t)f^3(t)) + f^4(t)]. \quad (25)$$

Hence the loop  $L(\sigma)$  exists if and only if for all  $w \in \mathbb{R}$  the inequality

$$0 < w^2(g'(t)f(t) + g(t)f'(t) + g^2(t)f^2(t) + 1) + w(-2f(t)f'(t) - 2g(t)f^3(t)) + f^4(t) \quad (26)$$

holds. For  $w = 0$  the expression (26) equals to  $f^4(t) > 0$ . Therefore the inequality (26) satisfies for all  $w \in \mathbb{R}$  if and only if one has

$$f'^2(t) + g(t)f^2(t)f'(t) - g'(t)f^3(t) - f^2(t) < 0 \quad \text{and} \quad g'(0) > f'^2(0) - 1 \quad (27)$$

for all  $t \in \mathbb{R}$ . Putting  $f(t) = \hat{f}^{-1}(t)$  and  $g(t) = -\hat{g}(t)$  these conditions are equivalent to the conditions

$$\hat{f}'^2(t) + \hat{g}(t)\hat{f}'(t) + \hat{g}'(t)\hat{f}(t) - \hat{f}^2(t) < 0 \quad \text{and} \quad \hat{g}'(0) < 1 - \hat{f}'^2(0) \quad (28)$$

(cf. [8], Section 18, (C), p. 238).

Now we treat the differential inequality (28). The solution  $h(t)$  of the linear differential equation

$$h'(t) + h(t)\frac{\hat{f}'(t)}{\hat{f}(t)} + \frac{\hat{f}'^2(t)}{\hat{f}(t)} - \hat{f}(t) = 0 \quad (29)$$

with the initial conditions  $h(0) = 0$  and  $h'(0) = 1 - \hat{f}'^2(0)$  is given by

$$h(t) = \hat{f}(t)^{-1} \int_0^t (\hat{f}^2(t) - \hat{f}'^2(t)) dt.$$

Since  $\hat{g}(0) = h(0) = 0$  and  $\hat{g}'(0) < h'(0)$  it follows from VI in [13] (p. 66) that  $\hat{g}(t)$  is a subfunction of the differential equation (29), i.e. that  $\hat{g}(t)$  satisfies the differential inequality (28). Moreover, according to Theorem V in [13] (p. 65) one has  $\hat{g}(t) < h(t)$  for all  $t \in (0, 2\pi)$ . Since the functions  $\hat{g}(t)$  and  $h(t)$  are continuous  $0 = \hat{g}(2\pi) \leq h(2\pi)$ . This yields the following integral inequality

$$\int_0^{2\pi} (\hat{f}^2(t) - \hat{f}'^2(t)) dt \geq 0. \quad (30)$$

We consider the real function  $R(t)$  defined by  $R(t) = \hat{f}(t) - \hat{f}'(t)$ . Since  $\hat{f}(0) = \hat{f}(2\pi) = 1$  and  $\hat{f}'(0) = \hat{f}'(2\pi)$  we have  $R(0) = 1 - \hat{f}'(0) = 1 - \hat{f}'(2\pi) = R(2\pi)$ .

The linear differential equation

$$y'(t) - y(t) + R(t) = 0 \quad \text{with} \quad y(0) = 1 \quad (31)$$

has the solution

$$y(t) = e^t \left( 1 - \int_0^t R(u) e^{-u} du \right). \quad (32)$$

This solution is unique (cf. [6], p. 2) and hence it is the function  $\hat{f}(t)$ .

The condition  $\hat{f}(2\pi) = 1$  is satisfied if and only if  $\int_0^{2\pi} R(u) e^{-u} du = 1 - \frac{1}{e^{2\pi}}$ .

Since  $R(t)$  has periode  $2\pi$  its Fourier series is given by

$$a_0 + \sum_{k=1}^{\infty} (a_k \cos kt + b_k \sin kt), \quad (33)$$

where  $a_0 = \frac{1}{\pi} \int_0^{2\pi} R(t) dt$ ,  $a_k = \frac{1}{\pi} \int_0^{2\pi} R(t) \cos kt dt$ , and  $b_k = \frac{1}{\pi} \int_0^{2\pi} R(t) \sin kt dt$ .

Partial integration yields

$$\int_0^t \sin ku e^{-u} du = \frac{k - k \cos kt e^{-t} - \sin kt e^{-t}}{1 + k^2} \quad (34)$$

$$\int_0^t \cos ku e^{-u} du = \frac{1 + k \sin kt e^{-t} - \cos kt e^{-t}}{1 + k^2}. \quad (35)$$

Using (34) and (35), we obtain by partial integration

$$\begin{aligned} \int_0^t R(u) e^{-u} du &= a_0 - a_0 e^{-t} + \sum_{k=1}^{\infty} \left[ \int_0^t a_k \cos ku e^{-u} du + \int_0^t b_k \sin ku e^{-u} du \right] = \\ a_0 - a_0 e^{-t} &+ \sum_{k=1}^{\infty} \frac{a_k (1 + k \sin kt e^{-t} - \cos kt e^{-t})}{1 + k^2} + \frac{b_k (k - k \cos kt e^{-t} - \sin kt e^{-t})}{1 + k^2}. \end{aligned} \quad (36)$$

Now for the real coefficients  $a_0, a_k, b_k$  ( $k \geq 1$ ) it follows

$$1 - \frac{1}{e^{2\pi}} = \int_0^{2\pi} R(u) e^{-u} du = \left( a_0 + \sum_{k=1}^{\infty} \frac{a_k + k b_k}{1 + k^2} \right) \left( 1 - \frac{1}{e^{2\pi}} \right).$$

Hence one has

$$a_0 + \sum_{k=1}^{\infty} \frac{a_k + kb_k}{1 + k^2} = 1. \quad (37)$$

The function  $\hat{f}(t)$  is positive if and only if

$$1 > \int_0^t R(u)e^{-u} du \quad \text{for all } t \in [0, 2\pi]. \quad (38)$$

Applying (34) and (35) again we see that the inequality (38) is equivalent to

$$a_0 > \sum_{k=1}^{\infty} \left[ \frac{a_k k - b_k}{1 + k^2} \sin kt - \frac{a_k + b_k k}{1 + k^2} \cos kt \right]. \quad (39)$$

Since  $\hat{f}'(t) + \hat{f}(t) = 2e^t(1 - \int_0^t R(u)e^{-u} du) - R(t)$  the function  $\hat{f}(t)$  satisfies the integral inequality (30) if and only if

$$\int_0^{2\pi} R(t) \left[ 2e^t \left( 1 - \int_0^t R(u)e^{-u} du \right) - R(t) \right] dt \geq 0. \quad (40)$$

The left side of (40) can be written as

$$2 \int_0^{2\pi} R(t)e^t dt - 2 \int_0^{2\pi} R(t)e^t \left( \int_0^t R(u)e^{-u} du \right) dt - \int_0^{2\pi} R^2(t) dt. \quad (41)$$

Using partial integration and representing  $R(u)$  by a Fourier series (33) we have

$$\int_0^{2\pi} R(t)e^t dt = \left( a_0 + \sum_{k=1}^{\infty} \frac{a_k - b_k k}{1 + k^2} \right) (e^{2\pi} - 1). \quad (42)$$

From (36) it follows

$$\begin{aligned} & \int_0^{2\pi} R(t)e^t \left( \int_0^t R(u)e^{-u} du \right) dt = \\ & a_0 \int_0^{2\pi} R(t)e^t dt - a_0 \int_0^{2\pi} R(t) dt + \sum_{k=1}^{\infty} \int_0^{2\pi} \left( \frac{a_k + kb_k}{1 + k^2} \right) R(t)e^t dt + \end{aligned}$$



$$\sum_{k=1}^{\infty} \int_0^{2\pi} \left( \frac{ka_k - b_k}{1 + k^2} \right) R(t) \sin kt \, dt - \sum_{k=1}^{\infty} \int_0^{2\pi} \left( \frac{a_k + kb_k}{1 + k^2} \right) R(t) \cos kt \, dt. \quad (43)$$

Substituting for  $R(t)$  its Fourier series and applying the relation (a) in [12] (p. 10) we have

$$\int_0^{2\pi} R(t) dt = 2\pi a_0.$$

Futhermore, one has

$$\begin{aligned} & \sum_{k=1}^{\infty} \int_0^{2\pi} \left( \frac{ka_k - b_k}{1 + k^2} \right) R(t) \sin kt \, dt = \\ & \sum_{k=1}^{\infty} \int_0^{2\pi} \left( \frac{ka_k - b_k}{1 + k^2} \right) [a_0 + \sum_{l=1}^{\infty} (a_l \cos lt + b_l \sin lt)] \sin kt \, dt = \\ & a_0 \sum_{k=1}^{\infty} \int_0^{2\pi} \left( \frac{ka_k - b_k}{1 + k^2} \right) \sin kt \, dt + \sum_{k=1}^{\infty} \sum_{l=1}^{\infty} \int_0^{2\pi} \left( \frac{ka_k - b_k}{1 + k^2} \right) a_l \cos lt \sin kt \, dt + \\ & \sum_{k=1}^{\infty} \sum_{l=1}^{\infty} \int_0^{2\pi} \left( \frac{ka_k - b_k}{1 + k^2} \right) b_l \sin lt \sin kt \, dt. \end{aligned}$$

The relations (a), (b), (c), (d) in [12], p. 10, yield

$$\sum_{k=1}^{\infty} \int_0^{2\pi} \left( \frac{ka_k - b_k}{1 + k^2} \right) R(t) \sin kt \, dt = \sum_{k=1}^{\infty} \int_0^{2\pi} \left( \frac{ka_k - b_k}{1 + k^2} \right) b_k \sin^2 kt \, dt = \sum_{k=1}^{\infty} \left( \frac{ka_k - b_k}{1 + k^2} \right) b_k \pi.$$

Analogously we obtain that

$$\sum_{k=1}^{\infty} \int_0^{2\pi} \left( \frac{a_k + kb_k}{1 + k^2} \right) R(t) \cos kt \, dt = \sum_{k=1}^{\infty} \int_0^{2\pi} \left( \frac{a_k + kb_k}{1 + k^2} \right) b_k \cos^2 kt \, dt = \sum_{k=1}^{\infty} \left( \frac{a_k + kb_k}{1 + k^2} \right) a_k \pi.$$

Using the equality (37) one has

$$\begin{aligned} & \int_0^{2\pi} R(t) e^t \left( \int_0^t R(u) e^{-u} du \right) dt = \\ & [a_0 + \sum_{k=1}^{\infty} \frac{a_k - kb_k}{1 + k^2}] (e^{2\pi} - 1) - \pi \sum_{k=1}^{\infty} \frac{b_k^2 + a_k^2}{1 + k^2} - 2\pi a_0^2. \quad (44) \end{aligned}$$

Substituting for  $R(t)$  its Fourier series we have

$$\begin{aligned} \int_0^{2\pi} R^2(t) dt &= \int_0^{2\pi} a_0^2 dt + 2a_0 \sum_{k=1}^{\infty} \int_0^{2\pi} (a_k \cos kt + b_k \sin kt) dt - \\ &\sum_{k=1}^{\infty} \sum_{l=1}^{\infty} \int_0^{2\pi} (a_k a_l \cos kt \cos lt + a_k b_l \cos kt \sin lt + \\ &b_k a_l \sin kt \cos lt + b_k b_l \sin kt \sin lt) dt. \end{aligned}$$

Applying the relations (a), (b), (c), (d) in [12] (p. 10) we obtain

$$\int_0^{2\pi} R^2(t) dt = 2\pi a_0^2 + \pi \sum_{k=1}^{\infty} (a_k^2 + b_k^2).$$

Hence the integral inequality (30) holds if and only if

$$2a_0 \geq \sum_{k=1}^{\infty} (a_k^2 + b_k^2) \frac{k^2 - 1}{k^2 + 1}.$$

Since the Fourier series of  $R(t)$  lies in the set  $\mathcal{F}$  of series the Fourier series of  $R$  converges uniformly to  $R$  (Lemma 5).

Summarizing our discussion we obtain the main part of the following

**Theorem 6.** *Let  $L$  be a 1-dimensional connected  $\mathcal{C}^1$ -differentiable loop such that the group topologically generated by its left translations is isomorphic to the group  $SL_2(\mathbb{R})$ . Then  $L$  is compact and belongs to a  $\mathcal{C}^1$ -differentiable sharply transitive section  $\sigma$  of the form*

$$\begin{aligned} \sigma : \left( \begin{array}{cc} \cos t & \sin t \\ -\sin t & \cos t \end{array} \right) \left\{ \left( \begin{array}{cc} a & b \\ 0 & a^{-1} \end{array} \right); a > 0, b \in \mathbb{R} \right\} \rightarrow \\ \left( \begin{array}{cc} \cos t & \sin t \\ -\sin t & \cos t \end{array} \right) \left( \begin{array}{cc} f(t) & g(t) \\ 0 & f^{-1}(t) \end{array} \right) \quad \text{with } t \in \mathbb{R} \end{aligned} \quad (45)$$

such that the inverse function  $f^{-1}$  has the shape

$$\begin{aligned} f^{-1}(t) &= e^t \left( 1 - \int_0^t R(u) e^{-u} du \right) = \\ a_0 + \sum_{k=1}^{\infty} \frac{(ka_k - b_k) \sin kt + (a_k + kb_k) \cos kt}{1 + k^2}, \end{aligned} \quad (46)$$

where  $R(u)$  is a continuous function the Fourier series of which is contained in the set  $\mathcal{F}$  and converges uniformly to  $R$ , and  $g$  is a periodic  $\mathcal{C}^1$ -differentiable function with  $g(0) = g(2\pi) = 0$  such that

$$g(t) > -f(t) \int_0^t \frac{(f^2(u) - f'^2(u))}{f^4(u)} du \text{ for all } t \in (0, 2\pi). \quad (47)$$

Conversely, if  $R(u)$  is a continuous function the Fourier series of which is contained in  $\mathcal{F}$ , then the section  $\sigma$  of the form (45) belongs to a loop if  $f$  is defined by (46) and  $g$  is a  $\mathcal{C}^1$ -differentiable periodic function with  $g(0) = g(2\pi) = 0$  satisfying (47).

The isomorphism classes of loops defined by  $\sigma$  are in one-to-one correspondence to the 2-sets  $\{(f(t), g(t)), (f(-t), -g(-t))\}$ .

*Proof.* The only part of the assertion which has to be discussed is the isomorphism question. It follows from [7], Theorem 3, p. 3, that any isomorphism class of the loops  $L$  contains precisely two pairs  $(f_1, g_1)$  and  $(f_2, g_2)$ . If  $(f_1, g_1) \neq (f_2, g_2)$  and if  $(f_1, g_1)$  satisfy the inequality (27), then we have

$$f_2'^2(-t) + g_2(-t)f_2^2(-t)f_2'(-t) - g_2'(-t)f_2^3(-t) - f_2^2(-t) < 0.$$

since from  $f_1(t) = f_2(-t)$  and  $g_1(t) = -g_2(-t)$  we have  $f_1'(t) = -f_2'(-t)$  and  $g_1'(t) = g_2'(-t)$ .  $\square$

*Remark.* A loop  $\tilde{L}$  belonging to a section  $\sigma$  of shape (45) is a 2-covering of a  $\mathcal{C}^1$ -differentiable loop  $L$  having the group  $PSL_2(\mathbb{R})$  as the group topologically generated by the left translations if and only if for the functions  $f$  and  $g$  one has  $f(\pi) = 1$  and  $g(\pi) = 0$  (cf. [9], p. 5106). Moreover,  $L$  is the factor loop  $\tilde{L}/\left\{\begin{pmatrix} \epsilon & 0 \\ 0 & \epsilon \end{pmatrix}; \epsilon = \pm 1\right\}$ . Any  $n$ -covering of  $L$  is a non-split central extension  $\hat{L}$  of the cyclic group of order  $n$  by  $L$ . The loop  $\hat{L}$  has the  $n$ -covering of  $PSL_2(\mathbb{R})$  as the group topologically generated by its left translations.

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